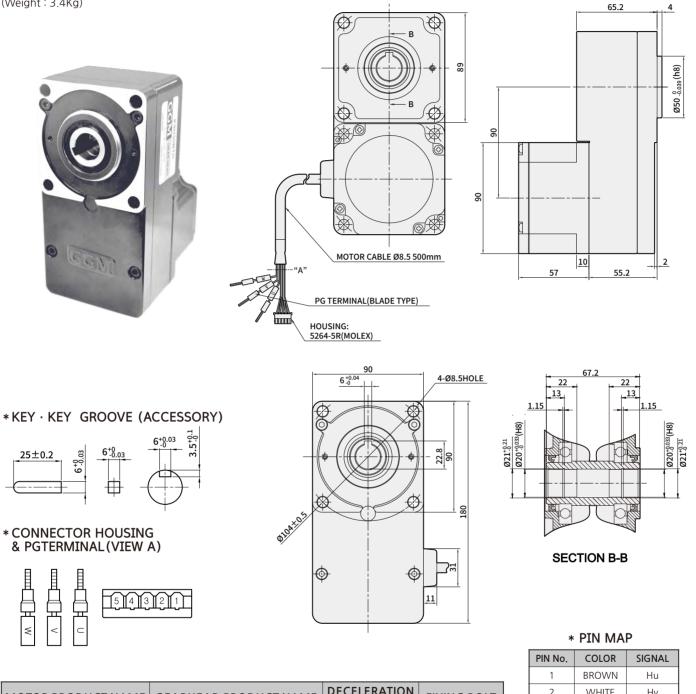
GGM GGM GEARED MOTOR

BRUSHLESS DC MOTOR UNIT - L Series

DIMENSIONS

K9LH100N2 + K9H□BTH

(Weight: 3.4Kg)



MOTOR PRODUCT NAME	GEARHEAD PRODUCT NAME	DECELERATION RATIO	FIXING BOLT	
K9LH100N2	К9Н□ВТН	5~200	M8 P1.25×90	

* In □ of name, it represents a deceleration ratio.

* Mounting bolt sets are included in flat type gearbox.

M8×90L (flat washer, spring washer, hexagonal nut 4pcs each)

2 WHITE Ηv ORANGE 3 Ηw GREEN 4 Ground YELLOW 5 Vcc -BLUE U _ PURPLE V

GRAY

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Specification

Product	GEAR TYPE	K6LH30N2	K8LH50N2	K9LH100N2			
name	D-CUT TYPE	K6LS30N2	K8LS50N2	K9LS100N2			
Rating outp	ut (continuous) W	30	50	100			
	Rating voltage V	DC24					
Power	Rating voltage allowance	±10%					
input	Rating input current A	2.1	3.1	6.0			
	Rating output current A	3.7	5.4	9.8			
Rating torqu	ue N·m(kgf·cm)	0.12	0.2	0.4			
Starting tore	que N·m(kgf·cm)	0.15	0.24	0.5			
Rating rotat	ion speed r/min	2500					
Speed contr	ol range r/min	100~3000					
Allowed iner of round sha	tia load moment J×10 ^{-₄} kg⋅m² ft type	1.8	3.3	5.6			
Rotor inertia	a moment J×10 ⁻⁴ kg·m ²	0.086	0.234	0.611			
	Load	Less than or equal to ±1% : condition 0-rated torque, rated rotation speed, rated voltage, room temperature					
Speed change rate	Voltage	Less than or equal to ±1% : condition rating voltage ±10%, rating rotation speed, no load, room temperature					
	Temperature	Less than or equal to ±1% : condition surrounding temperature 0~+40°C, rating rotation speed, no load, rating voltage					

* The usage duration for stabting torque is within 5 seconds at less than 2000 r/min

* Each specification value is the characteristic of motor by itself

Common specifications

Product name	Specification
Rotation speed setting method	 Set up by external potentiometer Set up by external DC 0~5V
Acceleration time deceleration time	0.5~10 seconds : set at 2000 r/min when there is no load (it may change depending on the size of the load) Accleration time and deceleration control equipment to control at the same time
Input signal	Internal full-up input method, external input voltage read as greater than 2v high(off) same at all input ports
Output signal	Open collector output, common for speed out/alarm out, if input voltage from out side is applied to connector #2 pin, then it comes out through the applied power. Everything else is internal 5V ouput UI(CTRL)
Protection function	 If the following protection mode comes on, cotrol unit alarm signal is shown. Motor stops automatically. Overload protection mode : If torque that is greater than the rating is applied to the motor for more than 5 seconds Overvoltage protection : If voltage applied to the control unit goes over the upper bound of the rating allowance Open phase protection : If cable sensor line gets disconnected during motor operation Undervoltage protection : If voltage applied to the control unit is less than the lower bound of th rating voltage allowance Over speed protection : If motor rotation speed is faster than 2500 r/min
Motor insulation class	E TYPE(120°C)
Maximum extension distance	MOTOR - CONTROL UNIT 2m
Rated time	Continuous

* Like weight carried being downwards, L SERIES cannot control motor speed through weight.

Motor gets stopped automatically through overvoltage protection of load is being carried downwards or it is heavier than allowed load inertia.

Normal specifications

lter	ns	Motor	Control unit			
Insulation Resistance		After being operated continuously at room temperature and humidity, the value measured between coil and vase by DC 500V MEGA is greater than or equal to 100\\Q	After being operated continuously at room temperature and humidity, the value measured between heatproof plate and power input is greater than or equal to 100 MQ			
Dielectric Strength		After being operated continuously at room temperature and humidity, there shouldn't be any problem between coil and case even when AC 0.5kV is applied for 1 minute	No problem when 50Hz, AC 0.5kV is applied for one minute No problem when AC 0.5kV is applied for one minute			
	Used Ambient temperature	0°c~+50°C (sho	ould not freeze)			
	Used Ambient Humidity	less than or equal to	85% (not from dews)			
Used	Vibration	Altitude less than 1000m				
environment	Ambient environment	Cannot be used under special circumstances such as with corrosive gas, dust, radioactive material, magnetic and vacuum				
	Vibration	Should not apply constant vibration or huge impact according to the JIS C 60068-2-6 sine wave vibration test method Frequency range : 10~55Hz, peak amplitude : 0.15mm, sweet direction : 3 direction(X,Y,Z), number of sweeps : 20 times				
	Ambient temperature	-25 ~ +70°C (should not freeze)				
Conservation environment	Ambient Humidity	less than or equal to 85% (not form dews)				
	Altitude	Altitude less	than 3000m			
Insulatio	on class	UL, CSA STANDARD A TYPE(105℃), EN STANDARD E TYPE(120℃)				
Protection class		IP65	IPOO			

* Preservation environment is a short-term value, which includes transportation.

* Do not measure insulation resistance and pressure resistance while motor and driver are connected

Allowed torque of combination type

				i		l		onic upp		ower part - kgr-cm
	Decelerat	ion ratio	5	10	15	20	30	50	100	200
Items	tems Speed control range [r/min]		20~500	10~250	6.7~167	5~125	3.3~83	2~50	1~25	0.5~12.5
Speed Control			600	300	200	150	100	60	30	15
K6LH30N2 + K6H□B		100~2500r/min	0.54 5.4	1.1 11	1.6 16	2.2 22	3.1 31	5.2 52	6 60	6 60
		3000r/min	0.27 2.7	0.54 5.4	0.81 8.1	1.1 11	1.5 15	2.6 26	5.2 52	6 60
Когп	50N2 + K8H□B	100~2500r/min	0.9 9	1.8 18	2.7 27	3.6 36	5.2 52	8.6 86	16 160	16 160
KOLU		3000r/min	0.45 4.5	0.9 9	1.4 14	1.8 18	2.6 26	4.3 43	8.6 86	16 160
	100N2 + K9H□B	100~2500r/min	1.8 18	3.6 36	5.4 54	7.2 72	10.3 103	17.2 172	30 300	30 300
KYLH		3000r/min	0.9 9	1.8 18	2.7 27	3.6 36	5.2 52	8.6 86	17.2 172	30 300
Kellia	0N2 + K6H□BTH	100~2500r/min	0.48 4.8	1 10	1.5 15	2 20	3.1 31	5.1 51	10.2 102	17 170
KOLHS		3000r/min	0.24 2.4	0.51 5.1	0.77 7.7	1 10	1.5 15	2.6 26	5.1 51	10.2 102
	0N2 + K8H□BTH	100~2500r/min	0.85 8.5	1.7 17	2.6 26	3.4 34	5.1 51	8.5 85	1~25 30 6 60 5.2 52 16 160 8.6 300 17.2 172 10.2 102 5.1	34 340
KOLHJ		3000r/min	0.43 4.3	0.85 8.5	1.3 13	1.7 17	2.6 26	4.3 43		17 170
		100~2500r/min	1.7 17	3.4 34	5.1 51	6.8 68	10.2 102	17 170		68 680
KATHI	00N2 + K9H□BTH	3000r/min	0.85 8.5	1.7 17	2.6 26	3.4 34	5.1 51	8.5 85		34 340

* Rotation direction shows the same color as the motor. In other cases, it's the opposite.

* Flat Gearbox viewed from front side is opposite rotation direction with motor. Flat Gearbox viewed from back side is same rotation direction with motor. Unit = upper part : N·m / lower part : kgf·cm

Allowed overhang load and allowed thrust

Product name				Allowed ov	Allowed thrust load			
		Deceleration ratio	From the end of output part : 10mm					From the end of output part :20mm
			N	kgf	N	kgf	N	kgf
	+ KOHLIB	5	100	10	150	15		4
		10~20	150	15	200	20	40	
		30~200	200	20	300	30		
		5	200	20	250	25		
	K8LH50N2 + K8H□B	10~20	300	30	350	35	100	
		30~200	450	45	550	55		
		5	300	30	400	40	150	15
GEARED	K9LH100N2 + K9H□B	10~20	400	40	500	50		
MOTOR		30~200	500	50	650	65		
	K6LH30N2	5~10	450	45	370	37	200	20
	+ K6H□BTH	15~200	500	50	400	40	200	20
	K8LH50N2	5~10	800	80	660	66	100 10	40
	+ K8H□BTH	15~200	1200	120	1000	100		40
		5~10	900	90	770	77		
	K9LH100N2 + K9H□BTH	15~20	1300	130	1110	111		50
		30~200	1500	150	1280	128		
	K6LS	30N2	70	7	100	10	If it's inevitable, keep it unde	
MOTOR	K8LS	50N2	120	12	140	14		
	K9LS1		160	16	170	17		

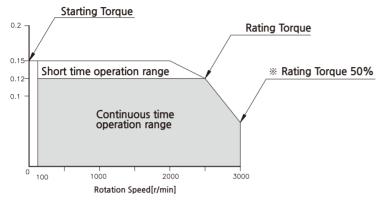
* In \square of name, it represents a deceleration ratio.

* Permissible overhang load can be withdrawn by calulation.

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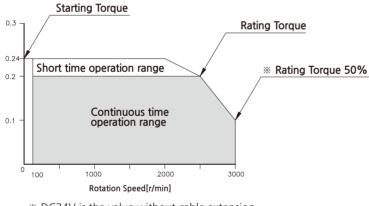
Rotation speed- torque characteristic

K6LS30N2 / K6LH30N2



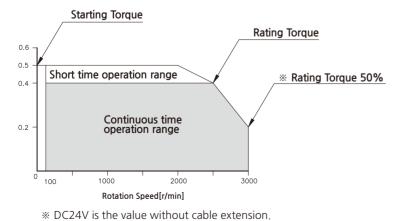
* DC24V is the value without cable extension.

K8LS50N2 / K8LH50N2



* DC24V is the value without cable extension.

K9LS100N2 / K9LH100N2



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